

NMEA 0183 Datensätze

Die Datensätze alphabetisch:

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Wind: [MWV](#) | [VPW](#) | [VWR](#) |

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AAM - Waypoint Arrival Alarm

1	2	3	4	5	6

\$--AAM,A,A,x.x,N,c--c*hh<CR><LF>

Field Number:

- 1) Status, BOOLEAN, A = Arrival circle entered
- 2) Status, BOOLEAN, A = perpendicular passed at waypoint
- 3) Arrival circle radius
- 4) Units of radius, nautical miles
- 5) Waypoint ID
- 6) Checksum

ABK - UAIS Addressed and binary broadcast acknowledgement

1	2	3	4	5

\$--ABK,xxxxxxxx,a,x.x,x,x*hh<CR><LF>

Field Number:

- 1) MMSI of the addressed AIS unit
- 2) AIS channel of reception
- 3) ITU-R M.1371 Message ID
- 4) Message sequence number
- 5) Type of acknowledgement

ACA - UAIS Regional Channel Assignment Message

No more information yet.

ACK - Acknowledge Alarm

1

\$--ACK,xxx*hh<CR><LF>

Field Number:

- 1) Unique alarm number (identifier) at alarm source

ACS - UAIS Channel management information Source

No more information yet.

AIR - UAIS Interrogation Request

No more information yet.

ALM - GPS Almanac Data

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16

\$--
ALM,x.x,x.x,xx,x.x,hh,hhhh,hh,hhhh,hhhh,hhhhhh,hhhhhh,hhhhhh,hhh,hhh,*hh<CR><LF>

Field Number:

- 1) Total number of messages
 - 2) Message Number
 - 3) Satellite PRN number (01 to 32)
 - 4) GPS Week Number :
- Date and time in GPS is computed as number of weeks from 6 January 1980 plus number of seconds into the week.
- 5) SV health, bits 17-24 of each almanac page
 - 6) Eccentricity
 - 7) Almanac Reference Time
 - 8) Inclination Angle
 - 9) Rate of Right Ascension
 - 10) Root of semi-major axis
 - 11) Argument of perigee
 - 12) Longitude of ascension node
 - 13) Mean anomaly
 - 14) F0 Clock Parameter
 - 15) F1 Clock Parameter
 - 16) Checksum

ALR - Set Alarm State

No more information yet.

APA - Autopilot Sentence "A"

	1	2	3	4	5	6	7	8	9	10		11

\$--APA,A,A,x.xx,L,N,A,A,xxx,M,c---c*hh<CR><LF>

Field Number:

1) Status

V = LORAN-C Blink or SNR warning

V = general warning flag or other navigation systems when a reliable fix is not available

2) Status

V = Loran-C Cycle Lock warning flag

A = OK or not used

3) Cross Track Error Magnitude

4) Direction to steer, L or R

5) Cross Track Units (Nautic miles or kilometers)

6) Status

A = Arrival Circle Entered

7) Status

A = Perpendicular passed at waypoint

8) Bearing origin to destination

9) M = Magnetic, T = True

10) Destination Waypoint ID

11) checksum

APB - Autopilot Sentence "B"

												13		15	
	1	2	3	4	5	6	7	8	9	10	11	12		14	

\$--APB,A,A,x.x,a,N,A,A,x.x,a,c--c,x.x,a,x.x,a*hh<CR><LF>

Field Number:

1) Status

V = LORAN-C Blink or SNR warning

V = general warning flag or other navigation systems when a reliable fix is not available

2) Status

V = Loran-C Cycle Lock warning flag

A = OK or not used

3) Cross Track Error Magnitude

4) Direction to steer, L or R

5) Cross Track Units, N = Nautical Miles

6) Status

A = Arrival Circle Entered

7) Status

A = Perpendicular passed at waypoint

8) Bearing origin to destination

9) M = Magnetic, T = True

10) Destination Waypoint ID

- 11) Bearing, present position to Destination
- 12) M = Magnetic, T = True
- 13) Heading to steer to destination waypoint
- 14) M = Magnetic, T = True
- 15) Checksum

ASD - Autopilot System Data

No more information yet.

BEC - Bearing & Distance to Waypoint - Dead Reckoning

											12		
1	2	3	4	5	6	7	8	9	10	11		13	

\$--BEC,hmmss.ss,1111.11,a,YYYY.YY,a,x.x,T,x.x,M,x.x,N,c--c*hh<CR><LF>

Field Number:

- 1) UTCTime
- 2) Waypoint Latitude
- 3) N = North, S = South
- 4) Waypoint Longitude
- 5) E = East, W = West
- 6) Bearing, True
- 7) T = True
- 8) Bearing, Magnetic
- 9) M = Magnetic
- 10) Nautical Miles
- 11) N = Nautical Miles
- 12) Waypoint ID
- 13) Checksum

BOD - Bearing Origin to Destination

1	2	3	4	5	6	7

\$--BOD,x.x,T,x.x,M,c--c,c--c*hh<CR><LF>

Field Number:

- 1) Bearing Degrees, TRUE
- 2) T = True
- 3) Bearing Degrees, Magnetic
- 4) M = Magnetic
- 5) TO Waypoint
- 6) FROM Waypoint
- 7) Checksum

BWC - Bearing and Distance to Waypoint, Latitude, N/S, Longitude, E/W, UTC, Status

											11		
1	2	3	4	5	6	7	8	9	10		12	13	

\$--BWC,hmmss.ss,1111.11,a,YYYY.YY,a,x.x,T,x.x,M,x.x,N,c--c*hh<CR><LF>

Field Number:

- 1) UTCTime
- 2) Waypoint Latitude
- 3) N = North, S = South
- 4) Waypoint Longitude
- 5) E = East, W = West
- 6) Bearing, True
- 7) T = True
- 8) Bearing, Magnetic
- 9) M = Magnetic
- 10) Nautical Miles
- 11) N = Nautical Miles
- 12) Waypoint ID
- 13) Checksum

BWR - Bearing and Distance to Waypoint - Rhumb Line, Latitude, N/S, Longitude, E/W, UTC, Status

	1	2	3	4	5	6	7	8	9	10	11	12	13
\$	--BWR	,hhmmss.ss	,lllll.ll	,a,YYYYY.yy	,a,x.x	,T,x.x	,M,x.x	,N,c	--c*hh	<CR><LF>			

Field Number:

- 1) UTCTime
- 2) Waypoint Latitude
- 3) N = North, S = South
- 4) Waypoint Longitude
- 5) E = East, W = West
- 6) Bearing, True
- 7) T = True
- 8) Bearing, Magnetic
- 9) M = Magnetic
- 10) Nautical Miles
- 11) N = Nautical Miles
- 12) Waypoint ID
- 13) Checksum

BWW - Bearing - Waypoint to Waypoint

	1	2	3	4	5	6	7
\$	--BWW	,x.x	,T,x.x	,M,c	--c	--c*hh	<CR><LF>

Field Number:

- 1) Bearing Degrees, TRUE
- 2) T = True
- 3) Bearing Degrees, Magnetic
- 4) M = Magnetic
- 5) TO Waypoint
- 6) FROM Waypoint
- 7) Checksum

CUR - Water Current Layer

No more information yet.

DBK - Depth Below Keel

```

      1   2 3   4 5   6 7
      |   |   |   |   |
$--DBK,x.x,f,x.x,M,x.x,F*hh<CR><LF>

```

Field Number:

- 1) Depth, feet
- 2) f = feet
- 3) Depth, meters
- 4) M = meters
- 5) Depth, Fathoms
- 6) F = Fathoms
- 7) Checksum

DBS - Depth Below Surface

```

      1   2 3   4 5   6 7
      |   | |   | |   | |
$--DBS,x.x,f,x.x,M,x.x,F*hh<CR><LF>

```

Field Number:

- 1) Depth, feet
- 2) f = feet
- 3) Depth, meters
- 4) M = meters
- 5) Depth, Fathoms
- 6) F = Fathoms
- 7) Checksum



DBT - Depth below transducer

```

      1   2 3   4 5   6 7
      |   | |   | |   | |
$--DBT,x.x,f,x.x,M,x.x,F*hh<CR><LF>

```

Field Number:

- 1) Depth, feet
- 2) f = feet
- 3) Depth, meters
- 4) M = meters
- 5) Depth, Fathoms
- 6) F = Fathoms
- 7) Checksum

DCN - Decca Position (obsolete)

										11	13		16		
1	2	3		4	5	6		7	8	9	10	12	14	15	17

\$--DCN,xx,cc,x.x,A,cc,x.x,A,cc,x.x,A,A,A,A,x.x,N,x*hh<CR><LF>

Field Number:

- 1) Decca chain identifier
- 2) Red Zone Identifier
- 3) Red Line Of Position
- 4) Red Master Line Status
- 5) Green Zone Identifier
- 6) Green Line Of Position
- 7) Green Master Line Status
- 8) Purple Zone Identifier
- 9) Purple Line Of Position
- 10) Purple Master Line Status
- 11) Red Line Navigation Use
- 12) Green Line Navigation Use
- 13) Purple Line Navigation Use
- 14) Position Uncertainty
- 15) N = Nautical Miles
- 16) Fix Data Basis
 - 1 = Normal Pattern
 - 2 = Lane Identification Pattern
 - 3 = Lane Identification Transmissions
- 17) Checksum

DPT - Depth of water

1	2	3

\$--DPT,x.x,x.x*hh<CR><LF>

Field Number:

- 1) Depth, meters
- 2) Offset from transducer,
 - positive means distance from transducer to water line
 - negative means distance from transducer to keel
- 3) Checksum

DSC - Digital Selective Calling Information

No more information yet.

DSE - Extended Digital Selective Calling

No more information yet.

DSI - Digital Selective Calling Transponder Initiate

No more information yet.

DSR - Digital Selective Calling Transponder Response

No more information yet.

DTM - Datum Reference

1	2	3	4	5	6	7	8	9

\$--DTM,xxx,x,xx.xxxx,x,xx.xxxx,x,,xxx*hh<CR><LF>

Field Number:

- 1) Local datum code
 - W84 - WGS84
 - W72 - WGS72
 - S85 - SGS85
 - P90 - PE90
 - 999 - User defined
- IHO datum code
- 2) Local datum sub code
- 3) Latitude offset (minute)
- 4) Latitude offset mark (N: +, S: -)
- 5) Longitude offset (minute)
- 6) Longitude offset mark (E: +, W: -)
- 7) Altitude offset (m) Always null
- 8) Datum
 - W84 - WGS84
 - W72 - WGS72
 - S85 - SGS85
 - P90 - PE90
 - ...
- 9) Checksum

FSI - Frequency Set Information

1	2	3	4	5

\$--FSI,xxxxxx,xxxxxx,c,x*hh<CR><LF>

Field Number:

- 1) Transmitting Frequency
- 2) Receiving Frequency
- 3) Communications Mode (NMEA Syntax 2)
- 4) Power Level
- 5) Checksum

GBS - GPS Satellite Fault Detection

1	2	3	4	5	6	7	8	9

\$--GBS,hhmmss.ss,x.x,x.x,x.x,x.x,x.x,x.x,x.x*hh<CR><LF>

Field Number:

- 1) UTC time of the GGA fix addociated with this sentence
- 2) Expected error in latitude
- 3) Expected error in longitude
- 4) Expected error in altitude
- 5) Most likely failed satellite
- 6) Probability of missed detection for most likely failed satellite
- 7) Estimate of bias on most likely failed satellite
- 8) Standard deviation on bias estimate
- 9) Checksum

GGA - Global Positioning System Fix Data, Time, Position and fix related data fora GPS receiver.

1	2	3 4	5 6 7 8	9	10		12 13	14	15

\$--GGA,hhmmss.ss,1111.11,a,yyyy.yy,a,x,xx,x.x,x.x,M,x.x,M,x.x,xxxx*hh<CR><LF>

- Field Number:
- 1) Universal Time Coordinated (UTC)
 - 2) Latitude
 - 3) N or S (North or South)
 - 4) Longitude
 - 5) E or W (East or West)
 - 6) GPS Quality Indicator,
 - 0 - fix not available,
 - 1 - GPS fix,
 - 2 - Differential GPS fix
 - 7) Number of satellites in view, 00 - 12
 - 8) Horizontal Dilution of precision
 - 9) Antenna Altitude above/below mean-sea-level (geoid)
 - 10) Units of antenna altitude, meters
 - 11) Geoidal separation, the difference between the WGS-84 earth ellipsoid and mean-sea-level (geoid), "-" means mean-sea-level below ellipsoid
 - 12) Units of geoidal separation, meters
 - 13) Age of differential GPS data, time in seconds since last SC104 type 1 or 9 update, null field when DGPS is not used
 - 14) Differential reference station ID, 0000-1023
 - 15) Checksum

GLC - Geographic Position, Loran-C

										12	14
1	2	3 4	5 6	7 8	9 10	11		13			

\$--GLC,xxxx,x.x,a,x.x,a,x.x,a,x,x,a,x.x,a,x.x,a*hh<CR><LF>

- Field Number:
- 1) GRI Microseconds/10
 - 2) Master TOA Microseconds
 - 3) Master TOA Signal Status
 - 4) Time Difference 1 Microseconds
 - 5) Time Difference 1 Signal Status
 - 6) Time Difference 2 Microseconds
 - 7) Time Difference 2 Signal Status
 - 8) Time Difference 3 Microseconds
 - 9) Time Difference 3 Signal Status
 - 10) Time Difference 4 Microseconds
 - 11) Time Difference 4 Signal Status
 - 12) Time Difference 5 Microseconds
 - 13) Time Difference 5 Signal Status
 - 14) Checksum

GLL - Geographic Position - Latitude/Longitude

1	2 3	4 5	6 7

\$--GLL,1111.11,a,yyyy.yy,a,hhmmss.ss,A*hh<CR><LF>

Field Number:

- 1) Latitude
- 2) N or S (North or South)
- 3) Longitude
- 4) E or W (East or West)
- 5) Universal Time Coordinated (UTC)
- 6) Status A - Data Valid, V - Data Invalid , P - Precise
- 7) Checksum

GMP - GNSS Map Projection Fix Data

No more information yet.

GNS - GNSS fixed data

1	2	3	4	5	6	7	8	9	10	11

\$--GNS,hhmmss.ss,1111.111,a,YYYYY.YYY,a,c--c,xx,x.x,x.x,x.x,x.x,x.x*hh<CR><LF>

Field Number:

- 1) UTC of position
- 2) Latitude, N/S
- 3) Longitude, E/W
- 4) Mode indicator
- 5) Total number of satllite in use,00-99
- 6) HDOP
- 7) Antenna altitude, metres, re:mean-sea-level(geoid)
- 8) Geoidal separation
- 9) Age of differential data
- 10) Differential reference station ID
- 11) Checksum

GRS - GNSS Range Residual

1	2	3

\$GPRGS,hhmmss,x,x.x,x.x,x.x,x.x,x.x,x.x,x.x,x.x,x.x,x.x,x.x,x.x*hh<CR><LF>

Field Number:

- 1) UTC time of GGA or GNS fix associated with this sentence
- 2) Mode
 - 0 = residuals were used to calculate the position given in the matching GGA or GNS.
 - 1 = residuals were computed after the GGA or GNS position was computed.
- 3) Range residuals in meters for sat. used in navigation solution. Order must match the order of the satellite ID numbers in GSA. When GRS is used GSA and GSV are generally required.

GSA - GPS DOP and active satellites

1	2	3	14	15	16	17	18

\$--GSA,a,a,x*hh<CR><LF>

Field Number:

- 1) Selection mode
- 2) Mode
- 3) ID of 1st satellite used for fix

- 4) ID of 2nd satellite used for fix
- ...
- 14) ID of 12th satellite used for fix
- 15) PDOP
- 16) HDOP
- 17) VDOP
- 18) checksum

GST - GNSS Pseudorange Error Statistics

```

      1      2      3      4      5      6      7      8
      |      |      |      |      |      |      |      |
$--GST,hhmmss.ss,x.x,x.x,x.x,x.x,x.x,x.x,x.x*hh<CR><LF>

```

- 1) UTC time of the GGA or GNS fix associated with this sentence.
- 2) RMS value of the standard deviation of the range inputs to the navigation process. Range inputs include pseudoranges & DGNSS corrections.
- 3) Standard deviation of semi-major axis of error ellipse (meters)
- 4) Standard deviation of semi-minor axis of error ellipse (meters)
- 5) Orientation of semi-major axis of error ellipse (degrees from true north)
- 6) Standard deviation of latitude error (meters)
- 7) Standard deviation of longitude error (meters)
- 8) Standard deviation of altitude error (meters)

This message is used to support Receiver Autonomous Integrity Monitoring (RAIM). Pseudorange measurement error statistics can be translated in the position domain in order to give statistical measures of the quality of the position solution.

If only GPS, GLONASS, etc. is used for the reported position solution, the talker ID is GP, GL, etc., and the error data pertains to the individual system. If satellites from multiple systems are used to obtain the reported position solution, the talker ID is GN and the errors pertain to the combined solution.

GSV - Satellites in view

```

      1  2  3  4  5  6  7      n
      |  |  |  |  |  |  |      |
$--GSV,x,x,x,x,x,x,x,...*hh<CR><LF>

```

- Field Number:
- 1) total number of messages
 - 2) message number
 - 3) satellites in view
 - 4) satellite number
 - 5) elevation in degrees
 - 6) azimuth in degrees to true
 - 7) SNR in dB
 - more satellite infos like 4)-7)
 - n) checksum

GTD - Geographic Location in Time Differences

```

      1      2      3      4      5      6
      |      |      |      |      |      |
$--GTD,x.x,x.x,x.x,x.x,x.x*hh<CR><LF>

```

Field Number:

- 1) time difference
- 2) time difference
- 3) time difference
- 4) time difference
- 5) time difference
- n) checksum

GXA - TRANSIT Position - Latitude/Longitude - Location and time of TRANSIT fix at waypoint (obsolete)

1	2	3 4	5 6	7 8

\$--GXA,hhmmss.ss,llll.ll,a,yyyy.yy,a,c--c,X*hh<CR><LF>

Field Number:

- 1) UTC of position fix
- 2) Latitude
- 3) East or West
- 4) Longitude
- 5) North or South
- 6) Waypoint ID
- 7) Satellite number
- 8) Checksum

HDG - Heading - Deviation & Variation

1	2	3 4	5 6

\$--HDG,x.x,x.x,a,x.x,a*hh<CR><LF>

Field Number:

- 1) Magnetic Sensor heading in degrees
- 2) Magnetic Deviation, degrees
- 3) Magnetic Deviation direction, E = Easterly, W = Westerly
- 4) Magnetic Variation degrees
- 5) Magnetic Variation direction, E = Easterly, W = Westerly
- 6) Checksum

HDM - Heading - Magnetic

1	2 3

\$--HDM,x.x,M*hh<CR><LF>

Field Number:

- 1) Heading Degrees, magnetic
- 2) M = magnetic
- 3) Checksum

HDT - Heading - True

1	2 3

\$--HDT,x.x,T*hh<CR><LF>

Field Number:

- 1) Heading Degrees, true
- 2) T = True
- 3) Checksum

HMR - Heading Monitor Receive

No more information yet.

HMS - Heading Monitor Set

No more information yet.

HSC - Heading Steering Command

	1	2	3	4	5

\$--HSC,x.x,T,x.x,M,*hh<CR><LF>

Field Number:

- 1) Heading Degrees, True
- 2) T = True
- 3) Heading Degrees, Magnetic
- 4) M = Magnetic
- 5) Checksum

HTC - Heading/Track Control Command

No more information yet.

HTD - Heading/Track Control Data

No more information yet.



LCD - Loran-C Signal Data

	1	2	3	4	5	6	7	8	9	10	11	12	13	14

\$--LCD,xxxx,xxx,xxx,xxx,xxx,xxx,xxx,xxx,xxx,xxx,xxx,xxx,xxx*hh<CR><LF>

Field Number:

- 1) GRI Microseconds/10
- 2) Master Relative SNR
- 3) Master Relative ECD
- 4) Time Difference 1 Microseconds
- 5) Time Difference 1 Signal Status
- 6) Time Difference 2 Microseconds
- 7) Time Difference 2 Signal Status
- 8) Time Difference 3 Microseconds
- 9) Time Difference 3 Signal Status
- 10) Time Difference 4 Microseconds
- 11) Time Difference 4 Signal Status
- 12) Time Difference 5 Microseconds
- 13) Time Difference 5 Signal Status
- 14) Checksum

LRF - UAIS Long-Range Function

No more information yet.

LRI - UAIS Long-Range Interrogation

No more information yet.

LR1 - UAIS Long-range Reply Sentence 1

No more information yet.

LR2 - UAIS Long-range Reply Sentence 2

No more information yet.

LR3 - UAIS Long-range Reply Sentence 3

No more information yet.

MLA - GLONASS Almanac Data

No more information yet.

MSK - MSK Receiver Interface (for DGPS Beacon Receivers)

1	2	3	4	5	6

\$--MSK,xxx.x,xx,xxx,xx,N*hh<CR><LF>

Field Number:

1) Frequency in kHz (283.5 to 325.0)

2) Frequency Selection

M1 = Manual

A1 = Automatic (field 1 empty)

3) MSK bit rate (100 or 200)

4) Bit Rate Selection

M2 = Manual

A2 = Automatic (field 3 empty)

5) Period of output of performance status message, 0 to 100 seconds (\$CRMSS)

6) Checksum

MSS - MSK Receiver Status Signal

No more information yet.

MTW - Water Temperature

1	2	3

\$--MTW,x.x,C*hh<CR><LF>

Field Number:

1) Degrees

2) Unit of Measurement, Celcius

3) Checksum

MWD - Wind Direction and Speed

No more information yet.

MWV - Wind Speed and Angle

1	2	3	4	5

\$--MWV,x.x,a,x.x,a*hh<CR><LF>

Field Number:

- 1) Wind Angle, 0 to 360 degrees
- 2) Reference, R = Relative, T = True
- 3) Wind Speed
- 4) Wind Speed Units, K/M/N
- 5) Status, A = Data Valid
- 6) Checksum

OLN - Omega Lane Numbers (obsolete)

1	2	3	4
-----+	-----+	-----+	
\$--OLN,aa,xxx,xxx,aa,xxx,xxx,aa,xxx,xxx*hh<CR><LF>			

Field Number:

- 1) Omega Pair 1
- 2) Omega Pair 1
- 3) Omega Pair 1
- 4) Checksum

OSD - Own Ship Data

	1	2	3	4	5	6	7	8	9	10
\$--	OSD	,	x.x	,	A,x.x	,	a,x.x	,	a,x.x	,x.x,a*hh<CR><LF>

Field Number:

- 1) Heading, degrees true
- 2) Status, A = Data Valid
- 3) Vessel Course, degrees True
- 4) Course Reference
- 5) Vessel Speed
- 6) Speed Reference
- 7) Vessel Set, degrees True
- 8) Vessel drift (speed)
- 9) Speed Units
- 10) Checksum

R00 - Waypoints in active route

```

      1              n
      |              |
$--R00,c---c,c---c,...*hh<CR><LF>

```

Field Number:

- 1) waypoint ID
...
n) checksum

RMA - Recommended Minimum Navigation Information

											12				
1	2			3	4			5	6	7	8	9	10	11	12

\$--RMA,A,1111.11,a,yyyyy.yy,a,x.x,x.x,x.x,x.x,x.x,a*hh<CR><LF>

Field Number:

- 1) Blink Warning
- 2) Latitude
- 3) N or S
- 4) Longitude
- 5) E or W
- 6) Time Difference A, uS
- 7) Time Difference B, uS
- 8) Speed Over Ground, Knots
- 9) Track Made Good, degrees true
- 10) Magnetic Variation, degrees
- 11) E or W
- 12) Checksum

RMB - Recommended Minimum Navigation Information

													14
	1	2	3	4	5	6	7	8	9	10	11	12	13

\$--RMB,A,x.x,a,c--c,c--c,1111.11,a,yyyyy.yy,a,x.x,x.x,x.x,A*hh<CR><LF>

Field Number:

- 1) Status, V = Navigation receiver warning
- 2) Cross Track error - nautical miles
- 3) Direction to Steer, Left or Right
- 4) TO Waypoint ID
- 5) FROM Waypoint ID
- 6) Destination Waypoint Latitude
- 7) N or S
- 8) Destination Waypoint Longitude
- 9) E or W
- 10) Range to destination in nautical miles
- 11) Bearing to destination in degrees True
- 12) Destination closing velocity in knots
- 13) Arrival Status, A = Arrival Circle Entered
- 14) Checksum

RMC - Recommended Minimum Navigation Information

												12
	1	2	3	4	5	6	7	8	9	10	11	

\$--RMC,hhmmss.ss,A,1111.11,a,yyyyy.yy,a,x.x,x.x,xxxx,x.x,a*hh<CR><LF>

Field Number:

- 1) UTC Time
- 2) Status, V = Navigation receiver warning, P = Precise
- 3) Latitude
- 4) N or S
- 5) Longitude
- 6) E or W
- 7) Speed over ground, knots
- 8) Track made good, degrees true

- 9) Date, ddmmyy
- 10) Magnetic Variation, degrees
- 11) E or W
- 12) Checksum

ROT - Rate Of Turn

1	2	3

\$--ROT,x.x,A*hh<CR><LF>

Field Number:

- 1) Rate Of Turn, degrees per minute, "-" means bow turns to port
- 2) Status, A means data is valid
- 3) Checksum

RPM - Revolutions

1	2	3	4	5	6

\$--RPM,a,x,x.x,x.x,A*hh<CR><LF>

Field Number:

- 1) Source, S = Shaft, E = Engine
- 2) Engine or shaft number
- 3) Speed, Revolutions per minute
- 4) Propeller pitch, % of maximum, "-" means astern
- 5) Status, A means data is valid
- 6) Checksum

RSA - Rudder Sensor Angle

1	2	3	4	5

\$--RSA,x.x,A,x.x,A*hh<CR><LF>

Field Number:

- 1) Starboard (or single) rudder sensor, "-" means Turn To Port
- 2) Status, A means data is valid
- 3) Port rudder sensor
- 4) Status, A means data is valid
- 5) Checksum

RSD - RADAR System Data

														14
1	2	3	4	5	6	7	8	9	10	11	12	13		

\$--RSD,x.x,x.x,x.x,x.x,x.x,x.x,x.x,x.x,x.x,x.x,x.x,a,a*hh<CR><LF>

Field Number:

- 9) Cursor Range From Own Ship
- 10) Cursor Bearing Degrees Clockwise From Zero
- 11) Range Scale
- 12) Range Units
- 14) Checksum

RTE - Routes

1	2	3	4	5		x	n

\$--RTE,x.x,x.x,a,c--c,c--c, c--c*hh<CR><LF>

Field Number:

1) Total number of messages being transmitted

2) Message Number

3) Message mode

c = complete route, all waypoints

w = working route, the waypoint you just left, the waypoint you're heading to then all the rest

4) Waypoint ID

x) More Waypoints

n) Checksum

SFI - Scanning Frequency Information

1	2	3	4		x

\$--SFI,x.x,x.x,xxxxxx,c xxxxxx,c*hh<CR><LF>

Field Number:

1) Total Number Of Messages

2) Message Number

3) Frequency 1

4) Mode 1

x) Checksum

SSD - UAIS Ship Static Data

No more information yet.

STN - Multiple Data ID

1	2

\$--STN,x.x,*hh<CR><LF>

Field Number:

1) Talker ID Number

2) Checksum

TLB - Target Label

No more information yet.

TLL - Target latitude and longitude

1	2		3		4	5		6	7	8

\$--TLL,xx,1111.111,a,yyyyy.yyy,a,c--c,hmmss.ss,a,a*hh<CR><LF>

Field Number:

1) Target number 00 - 99

2) Latitude, N/S

3) Longitude, E/W

4) Target name

- 5) UTC of data
- 6) Target status(see note)
 - L = lost,tracked target has beenlost
 - Q = query,target in the process of acquisition
 - T = tracking
- 7) Reference target=R,null otherwise
- 8) Checksum



TRF - TRANSIT Fix Data (obsolete)

	1	2	3	4	5	6	7	8	9	10	11	12	13

\$--TRF,hhmmss.ss,xxxxxx,1111.11,a,yyyy.yy,a,x.x,x.x,x.x,x.x,xxx,A*hh<CR><LF>

Field Number:

- 1) UTC Time
- 2) Date, ddmmyy
- 3) Latitude
- 4) N or S
- 5) Longitude
- 6) E or W
- 7) Elevation Angle
- 8) Number of iterations
- 9) Number of Doppler intervals
- 10) Update distance, nautical miles
- 11) Satellite ID
- 12) Data Validity
- 13) Checksum

TTM - Tracked Target Message

	1	2	3	4	5	6	7	8	9	10	11	12	13	14

\$--TTM,xx,x.x,x.x,a,x.x,x.x,a,x.x,x.x,a,c--c,a,a*hh<CR><LF>

Field Number:

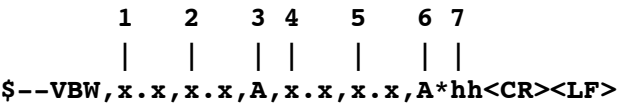
- 1) Target Number
- 2) Target Distance
- 3) Bearing from own ship
- 4) Bearing Units
- 5) Target speed
- 6) Target Course
- 7) Course Units
- 8) Distance of closest-point-of-approach
- 9) Time until closest-point-of-approach "-" means increasing
- 10) "-" means increasing
- 11) Target name

- 12) Target Status
- 13) Reference Target
- 14) Checksum

TUT - Transmission of Multi-Language Text
 No more information yet.

TXT - Text Transmission
 No more information yet.

VBW - Dual Ground/Water Speed

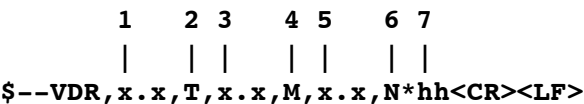


- Field Number:
- 1) Longitudinal water speed, "-" means astern
 - 2) Transverse water speed, "-" means port
 - 3) Status, A = Data Valid
 - 4) Longitudinal ground speed, "-" means astern
 - 5) Transverse ground speed, "-" means port
 - 6) Status, A = Data Valid
 - 7) Checksum

VDM - AIS VHF Datalink Message. AIS NMEA sentence that contains data about another ship.
 Information: <http://gpsd.berlios.de/AIVDM.html>

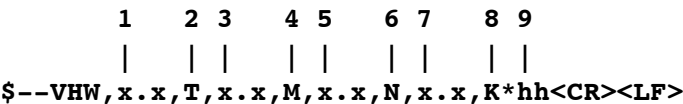
VDO - AIS VHF Datalink Own-vessel Message. AIS NMEA sentence that contains data about own ship.
 Information: <http://gpsd.berlios.de/AIVDM.html>

VDR - Set and Drift



- Field Number:
- 1) Degress True
 - 2) T = True
 - 3) Degrees Magnetic
 - 4) M = Magnetic
 - 5) Knots (speed of current)
 - 6) N = Knots
 - 7) Checksum

VHW - Water speed and heading



Field Number:

- 1) Degress True
- 2) T = True
- 3) Degrees Magnetic
- 4) M = Magnetic
- 5) Knots (speed of vessel relative to the water)
- 6) N = Knots
- 7) Kilometers (speed of vessel relative to the water)
- 8) K = Kilometers
- 9) Checksum

VLW - Distance Traveled through Water

	1	2	3	4	5

\$--VLW,x.x,N,x.x,N*hh<CR><LF>

Field Number:

- 1) Total cumulative distance
- 2) N = Nautical Miles
- 3) Distance since Reset
- 4) N = Nautical Miles
- 5) Checksum

VPW - Speed - Measured Parallel to Wind

	1	2	3	4	5

\$--VPW,x.x,N,x.x,M*hh<CR><LF>

Field Number:

- 1) Speed, "-" means downwind
- 2) N = Knots
- 3) Speed, "-" means downwind
- 4) M = Meters per second
- 5) Checksum

VSD - UAIS Voyage Static Data

VTG - Track made good and Ground speed

	1	2	3	4	5	6	7	8	9

\$--VTG,x.x,T,x.x,M,x.x,N,x.x,K*hh<CR><LF>

Field Number:

- 1) Track Degrees
- 2) T = True
- 3) Track Degrees
- 4) M = Magnetic
- 5) Speed Knots
- 6) N = Knots
- 7) Speed Kilometers Per Hour
- 8) K = Kilometers Per Hour
- 9) Checksum

VWR - Relative Wind Speed and Angle

	1	2	3	4	5	6	7	8	9

\$--VWR,x.x,a,x.x,N,x.x,M,x.x,K*hh<CR><LF>

Field Number:

- 1) Wind direction magnitude in degrees
- 2) Wind direction Left/Right of bow
- 3) Speed
- 4) N = Knots
- 5) Speed
- 6) M = Meters Per Second
- 7) Speed
- 8) K = Kilometers Per Hour
- 9) Checksum

WCV - Waypoint Closure Velocity

	1	2	3	4

\$--WCV,x.x,N,c--c*hh<CR><LF>

Field Number:

- 1) Velocity
- 2) N = knots
- 3) Waypoint ID
- 4) Checksum

WNC - Distance - Waypoint to Waypoint

	1	2	3	4	5	6	7

\$--WNC,x.x,N,x.x,K,c--c,c--c*hh<CR><LF>

Field Number:

- 1) Distance, Nautical Miles
- 2) N = Nautical Miles
- 3) Distance, Kilometers
- 4) K = Kilometers
- 5) TO Waypoint
- 6) FROM Waypoint
- 7) Checksum

WPL - Waypoint Location

	1	2	3	4	5	6

\$--WPL,1111.11,a,yyyyy.yy,a,c--c*hh<CR><LF>

Field Number:

- 1) Latitude
- 2) N or S (North or South)
- 3) Longitude
- 4) E or W (East or West)
- 5) Waypoint name
- 6) Checksum

XDR - Transducer Measurement

1	2	3	4			n

\$--XDR,a,x.x,a,c--c, *hh<CR><LF>

Field Number:

- 1) Transducer Type
- 2) Measurement Data
- 3) Units of measurement
- 4) Name of transducer
- x) More of the same
- n) Checksum

XTE - Cross-Track Error, Measured

1	2	3	4	5	6

\$--XTE,A,A,x.x,a,N,*hh<CR><LF>

Field Number:

- 1) Status
V = LORAN-C Blink or SNR warning
V = general warning flag or other navigation systems when a reliable fix is not available
- 2) Status
V = Loran-C Cycle Lock warning flag
A = OK or not used
- 3) Cross Track Error Magnitude
- 4) Direction to steer, L or R
- 5) Cross Track Units, N = Nautical Miles
- 6) Checksum

XTR - Cross Track Error - Dead Reckoning

1	2	3	4

\$--XTR,x.x,a,N*hh<CR><LF>

Field Number:

- 1) Magnitude of cross track error
- 2) Direction to steer, L or R
- 3) Units, N = Nautical Miles
- 4) Checksum

ZDA - Time & Date - UTC, day, month, year and local time zone

1	2	3	4	5	6	7

\$--ZDA,hmmss.ss,xx,xx,xxxx,xx,xx*hh<CR><LF>

Field Number:

- 1) Local zone minutes description, same sign as local hours
- 2) Local zone description, 00 to +- 13 hours
- 3) Year
- 4) Month, 01 to 12

- 5) Day, 01 to 31
- 6) Universal Time Coordinated (UTC)
- 7) Checksum



ZDL - Time and Distance to Variable Point

ZFO - UTC & Time from origin Waypoint

1	2	3	4

\$--ZFO,hhmmss.ss,hhmmss.ss,c--c*hh<CR><LF>

Field Number:

- 1) Universal Time Coordinated (UTC)
- 2) Elapsed Time
- 3) Origin Waypoint ID
- 4) Checksum

ZTG - UTC & Time to Destination Waypoint

1	2	3	4

\$--ZTG,hhmmss.ss,hhmmss.ss,c--c*hh<CR><LF>

Field Number:

- 1) Universal Time Coordinated (UTC)
- 2) Time Remaining
- 3) Destination Waypoint ID
- 4) Checksum

New found : (data fields unknown)

ABM - Addressed Binary Message

ALA - Set Detail Alarm Condition

ASM - Addressed Safety Message

BBM - Broadcast Binary Message

BSM - Broadcast Safety Message

ETL - Engine Telegraph Operation Status

EVE - General Event Message

FIR - Fire Detection

GAL - Galileo Almanac Data

GEN - Generic Status Information

GFA - GNSS Fix Accuracy and Integrity

HBT - Heartbeat Supervision Report

HSS - Hull Stress Surveillance System

NRM - NAVTEX Receiver Masl Command

TRC - Thruster Contro Data

TRD - Thruster Response Data

TTD - Tracked Target Date (Radar)

SNU - Loran - C SNR Status

WAT - Water Level Detection

WDC - Distance to Waypoint - Great Circle

WDR - Distance to Waypoint - Rhumb Line

NMEA 0183 Datensätze

Letzte Änderung 12.2013